

### High-voltage, high-side current sense amplifier

#### **Features**

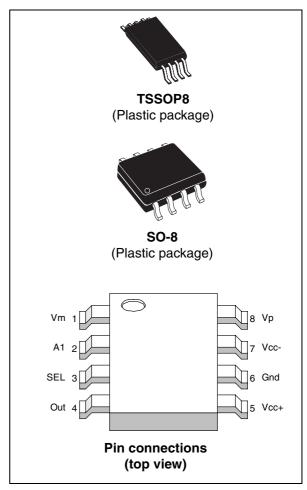
- Independent supply and input common-mode voltages
- Wide common-mode operating range:
   2.9 to 70 V in single-supply configuration
   -2.1 to 65 V in dual-supply configuration
- Wide common-mode surviving range:
   -16 to 75 V (reversed battery and load-dump conditions)
- Supply voltage range:2.7 to 5.5 V in single supply configuration
- Low current consumption: I<sub>CC</sub> max = 360 µA
- Pin selectable gain: 50 V/V or 100 V/V
- Buffered output
- EMI filtering

#### **Applications**

- Automotive current monitoring
- DC motor control
- Photovoltaic systems
- Battery chargers
- Precision current sources
- Current monitoring of notebook computers
- Uninterruptible power supplies
- High-end power supplies

#### **Description**

The TSC1031 measures a small differential voltage on a high-side shunt resistor and translates it into a ground-referenced output voltage. The TSC1031's dedicated schematic eases the implementation of EMI filtering in harsh environments. The gain is adjustable to 50 V/V or 100 V/V by a selection pin.



Wide input common-mode voltage range, low quiescent current, and tiny TSSOP8 packaging enable use in a wide variety of applications.

The input common-mode and power supply voltages are independent. The common-mode voltage can range from 2.9 to 70 V in the single-supply configuration or be offset by an adjustable voltage supplied on the Vcc- pin in the dual-supply configuration.

With a current consumption lower than 360  $\mu A$  and a virtually null input leakage current in standby mode, the power consumption in the applications is minimized.

Contents TSC1031

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## 1 Application schematic and pin description

The TSC1031 high-side current sense amplifier can be used in either single- or dual-supply mode. In the single-supply configuration, the TSC1031 features a wide 2.9 V to 70 V input common-mode range totally independent of the supply voltage. In the dual-supply range, the common-mode range is shifted by the value of the negative voltage applied on the Vcc-pin. For instance, with Vcc+=5 V and Vcc-=-5 V, then the input common-mode range is -2 V to 65 V.

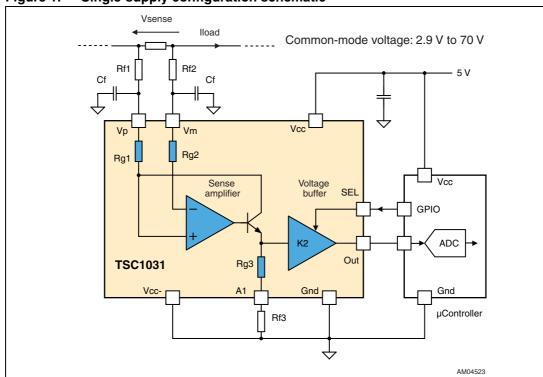


Figure 1. Single-supply configuration schematic

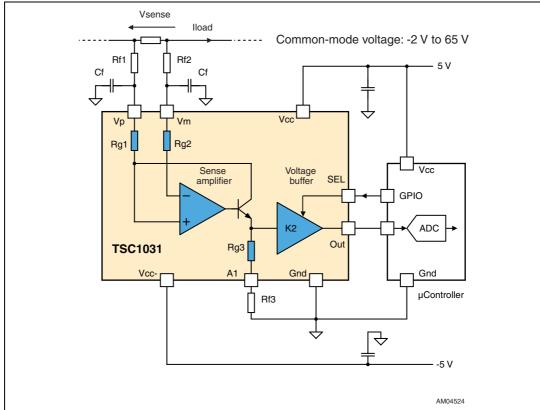


Figure 2. Dual-supply configuration schematic

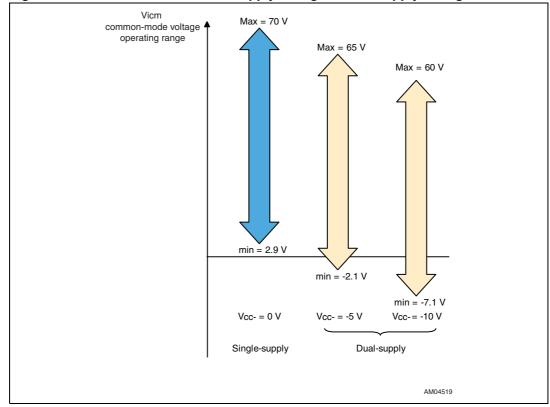


Figure 3. Common-mode versus supply voltage in dual-supply configuration

*Table 1* describes the function of each pin. Their position is shown in the illustration on the cover page and in *Figure 1 on page 3*.

Table 1. Pin description

Symbol	Туре	Function
Out	Analog output	The Out voltage is proportional to the magnitude of the sense voltage $V_p\text{-}V_m$ .
Gnd	Power supply	Ground line.
Vcc+	Power supply	Positive power supply line.
Vcc-	Power supply	Negative power supply line.
Vp	Analog input	Connection for the external sense resistor. The measured current enters the shunt on the $\rm V_{\rm p}$ side.
Vm	Analog input	Connection for the external sense resistor. The measured current exits the shunt on the $\rm V_{\rm m}$ side.
SEL	Digital input	Gain-select pin.
A1	Analog output	Connection to the output resistor.

## 2 Absolute maximum ratings and operating conditions

Table 2. Absolute maximum ratings

Table 2.	Absolute maximum ratings		
Symbol	Parameter	Value	Unit
V <sub>id</sub>	Input pins differential voltage (V <sub>p</sub> -V <sub>m</sub> )	±20	V
V <sub>in_sense</sub>	Sensing pins input voltages $(V_p, V_m)^{(1)}$	-16 to 75	V
V <sub>in_sel</sub>	Gain selection pin input voltage (SEL) <sup>(2)</sup>	-0.3 to V <sub>cc+</sub> +0.3	V
V <sub>in_A1</sub>	A1 pin input voltage <sup>(2)</sup>	-0.3 to V <sub>cc+</sub> +0.3	V
V <sub>cc+</sub>	Positive supply voltage <sup>(2)</sup>	-0.3 to 7	V
V <sub>CC+</sub> -V <sub>CC-</sub>	DC supply voltage	0 to 15	V
V <sub>out</sub>	DC output pin voltage <sup>(2)</sup>	-0.3 to V <sub>cc+</sub> +0.3	V
T <sub>stg</sub>	Storage temperature	-55 to 150	°C
T <sub>j</sub>	Maximum junction temperature	150	°C
D	TSSOP8 thermal resistance junction to ambient	120	°C/W
R <sub>thja</sub>	SO8 thermal resistance junction to ambient	125	°C/W
	HBM: human body model <sup>(3)</sup>	2.5	kV
ESD	MM: machine model <sup>(4)</sup>	150	V
	CDM: charged device model <sup>(5)</sup>	1.5	kV

<sup>1.</sup> These voltage values are measured with respect to the  $V_{\rm cc}$ - pin.

Table 3. Operating conditions

Symbol	Parameter	Value	Unit
V <sub>cc+</sub>	DC supply voltage in single-supply configuration from $T_{min}$ to $T_{max}$ ( $V_{cc}$ - connected to Gnd = 0 V)	2.7 to 5.5	٧
	Negative supply voltage in dual-supply configuration from T <sub>min</sub> to T <sub>max</sub>		
V <sub>cc-</sub>	V <sub>cc+</sub> = 5.5 V max	-8 to 0	V
	V <sub>cc+</sub> = 3 V max	-11 to 0	V
V <sub>icm</sub>	Common-mode voltage range referred to pin Vcc - $(T_{min} \text{ to } T_{max})$	2.9 to 70	٧
T <sub>oper</sub>	Operational temperature range (T <sub>min</sub> to T <sub>max</sub> )	-40 to 125	°C

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<sup>2.</sup> These voltage values are measured with respect to the Gnd pin.

<sup>3.</sup> Human body model: a 100 pF capacitor is charged to the specified voltage, then discharged through a 1.5 k $\Omega$  resistor between two pins of the device. This is done for all couples of connected pin combinations while the other pins are floating.

<sup>4.</sup> Machine model: a 200 pF capacitor is charged to the specified voltage, then discharged directly between two pins of the device with no external series resistor (internal resistor < 5  $\Omega$ ). This is done for all couples of connected pin combinations while the other pins are floating.

Charged device model: all pins plus package are charged together to the specified voltage and then discharged directly to ground.

#### 3 Electrical characteristics

The electrical characteristics given in the following tables are measured under the following test conditions unless otherwise specified.

- $T_{amb} = 25^{\circ} \text{ C}$ ,  $V_{cc+} = 5 \text{ V}$ ,  $V_{cc-}$  connected to Gnd (single-supply configuration).
- $\bullet$  V<sub>sense</sub> = V<sub>p</sub>-V<sub>m</sub> = 50 mV, V<sub>m</sub> = 12 V, no load on Out, all gain configurations.
- Rf1, Rf2 and Rf3 resistors are short-circuited.

#### Table 4. Supply

Symbol	Parameter	Test conditions	Min.	Тур.	Max.	Unit
I <sub>CC</sub>	Total supply current	V <sub>sense</sub> = 0 V, T <sub>min</sub> < T <sub>amb</sub> < T <sub>max</sub>		200	360	μΑ
I <sub>CC1</sub>	Total supply current	$V_{sense} = 50 \text{ mV Av} = 50 \text{ V/V}$ $T_{min} < T_{amb} < T_{max}$		300	480	μΑ

Table 5. Input

Symbol	Parameter	Test conditions	Min.	Тур.	Max.	Unit
DC CMR	DC common-mode rejection Variation of V <sub>out</sub> versus V <sub>icm</sub> referred to input <sup>(1)</sup>	2.9 V< V <sub>m</sub> < 70 V T <sub>min</sub> < T <sub>amb</sub> < T <sub>max</sub>	90	105		dB
AC CMR	AC common-mode rejection Variation of V <sub>out</sub> versus V <sub>icm</sub> referred to input (peak-to-peak voltage variation)	Av = 50 V/V or 100 V/V 2.9 V< V <sub>icm</sub> < 30 V 1 kHz sine wave		95		dB
SVR	Supply voltage rejection Variation of V <sub>out</sub> versus V <sub>CC</sub> <sup>(2)</sup>	Av = 50 V/V 2.7 V< V <sub>CC</sub> < 5.5 V V <sub>sense</sub> = 30 mV	85	100		dB
V <sub>os</sub>	Input offset voltage <sup>(3)</sup>	$T_{amb} = 25^{\circ} C$ $T_{min} < T_{amb} < T_{max}$			±500 ±1100	μV
dV <sub>os</sub> /dT	Input offset drift vs. T	$Av = 50 \text{ V/V}$ $T_{min} < T_{amb} < T_{max}$	-20		+5	μV/°C
I <sub>lk</sub>	Input leakage current	V <sub>CC</sub> = 0 V			1	μΑ
I <sub>ib</sub>	Input bias current	V <sub>sense</sub> = 0 V		10	15	μΑ
Rg1	Input resistor value			5		k $\Omega$
V <sub>IL</sub>	Logic low voltage (SEL)	V <sub>CCmin</sub> < V <sub>CC</sub> < V <sub>CCmax</sub>	-0.3		0.5	V
V <sub>IH</sub>	Logic high voltage (SEL)	V <sub>CCmin</sub> < V <sub>CC</sub> < V <sub>CCmax</sub>	1.2		$V_{CC}$	V
I <sub>sel</sub>	Gain-select pins (SEL) leakage input current	SEL pin connected to GND or V <sub>CC</sub>		400		nA

- 1. See Chapter 4: Parameter definitions on page 10 for the definition of CMR.
- 2. See Chapter 4 for the definition of SVR.
- 3. See Chapter 4 for the definition of  $V_{os}$ .

Table 6. Output

Symbol	Parameter	Test conditions	Min.	Тур.	Max.	Unit
K1	Sense amplifier gain (K1 = Rg3/Rg1)			25		
K2	Voltage buffer gain	SEL= Gnd SEL= Vcc+		2 4		
Av	Total gain (Av = K1.K2)	SEL= Gnd SEL= Vcc+		50 100		V/V
$\Delta V_{out}/\Delta T$	Output voltage drift vs. T <sup>(1)</sup>	$Av = 50 \text{ V/V}$ $T_{min} < T_{amb} < T_{max}$			±240	ppm/°C
$\Delta V_{out} / \Delta I_{out}$	Output stage load regulation	-10 mA < I <sub>out</sub> <10 mA I <sub>out</sub> sink or source current Av = 50 V/V, T <sub>amb</sub> = 25° C		0.3	±1.5	mV/mA
$\Delta V_{ m out}$	Total output voltage accuracy <sup>(2)</sup>	$V_{sense} = 50 \text{ mV}^{(3)}$ $T_{amb} = 25^{\circ} \text{ C}$ $T_{min} < T_{amb} < T_{max}$			±2.5 ±4	%
$\Delta V_{ m out}$	Total output voltage accuracy	$V_{sense} = 90 \text{ mV}^{(3)}$ $T_{amb} = 25^{\circ} \text{ C}$ $T_{min} < T_{amb} < T_{max}$			±3.5 ±5	%
$\Delta V_{out}$	Total output voltage accuracy	$V_{sense}$ = 20 mV $T_{amb}$ = 25° C $T_{min}$ < $T_{amb}$ < $T_{max}$			±3.5 ±5	%
$\Delta V_{out}$	Total output voltage accuracy	$V_{sense}$ = 10 mV $T_{amb}$ = 25° C $T_{min}$ < $T_{amb}$ < $T_{max}$			±5.5 ±8	%
$\Delta V_{out}$	Total output voltage accuracy	$V_{sense}$ = 5 mV $T_{amb}$ = 25° C $T_{min}$ < $T_{amb}$ < $T_{max}$			±10 ±22	%
I <sub>sc</sub>	Short-circuit current	OUT connected to V <sub>CC</sub> or GND	15	26		mA
V <sub>OH</sub>	Output stage high-state saturation voltage $V_{OH} = V_{CC} - V_{out}$	V <sub>sense</sub> = 1 V I <sub>out</sub> = 1 mA		85	135	mV
V <sub>OL</sub>	Output stage low-state saturation voltage	V <sub>sense</sub> = -1 V I <sub>out</sub> = 1 mA		80	125	mV

<sup>1.</sup> See Chapter 4: Parameter definitions on page 10 for the definition of output voltage drift versus temperature.

The output voltage accuracy is the difference with the expected theoretical output voltage V<sub>out-th</sub> = Av\*V<sub>sense</sub>. See Chapter 4 for a more detailed definition.

<sup>3.</sup> Except for Av = 100 V/V.

Table 7. Frequency response

Symbol	Parameter Test conditions		Min.	Тур.	Max.	Unit
		$V_{sense}$ = 10 mV to 100 mV, $C_{load}$ = 47 pF				
ts	Output settling to 1% of final value	Av = 50 V/V		6		μs
		Av = 100 V/V		10		μs
t <sub>SEL</sub>	Output settling to 1% of final value	Any change of state of SEL		1		
t <sub>rec</sub>	Response to common-mode voltage change. Output settling to 1% of final value	$V_{cc+}$ = 5 V, $V_{cc-}$ = -5 V $V_m$ step change from -2 V to 30 V or 30 V to -2 V		20		μs
SR	Slew rate	V <sub>sense</sub> = 10 mV to 100 mV	0.4	0.6		V/µs
BW	3 dB bandwidth	$C_{load}$ = 47 pF $V_{icm}$ = 12 V $V_{sense}$ = 50 mV $Av$ = 50 V/V		700		kHz

Table 8. Noise

Symbol	Parameter	Test conditions	Min.	Тур.	Max.	Unit
eN	Equivalent input noise voltage	f = 1 kHz		40		nV/√ <del>Hz</del>

Parameter definitions TSC1031

#### 4 Parameter definitions

#### 4.1 Common mode rejection ratio (CMR)

The common mode rejection ratio (CMR) measures the ability of the current sensing amplifier to reject any DC voltage applied on both inputs  $V_p$  and  $V_m$ . The CMR is referred back to the input so that its effect can be compared with the applied differential signal. The CMR is defined by the formula:

$$CMR = -20 \cdot \log \frac{\Delta V_{out}}{\Delta V_{icm} \cdot Av}$$

#### 4.2 Supply voltage rejection ratio (SVR)

The supply voltage rejection ratio (SVR) measures the ability of the current-sensing amplifier to reject any variation of the supply voltage  $V_{CC}$ . The SVR is referred back to the input so that its effect can be compared with the applied differential signal. The SVR is defined by the formula:

$$SVR = -20 \cdot log \frac{\Delta V_{out}}{\Delta V_{CC} \cdot Av}$$

### 4.3 Gain (Av) and input offset voltage (Vos)

The input offset voltage is defined as the intersection between the linear regression of the  $V_{out}$  vs.  $V_{sense}$  curve with the X-axis (see *Figure 4*.). If  $V_{out1}$  is the output voltage with  $V_{sense} = V_{sense2}$ , then  $V_{os}$  can be calculated with the following formula.

$$V_{os} = V_{sense1} - \left( \frac{V_{sense1} - V_{sense2}}{V_{out1} - V_{out2}} \cdot V_{out1} \right)$$

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TSC1031 Parameter definitions

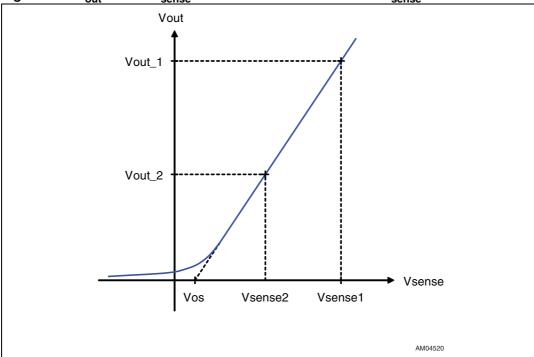


Figure 4.  $V_{out}$  versus  $V_{sense}$  characteristics: detail for low  $V_{sense}$  values

The values of  $V_{\text{sense1}}$  and  $V_{\text{sense2}}$  used for the input offset calculations are detailed in *Table 9*.

Table 9. Test conditions for  $V_{os}$  voltage calculation

Av (V/V)	V <sub>sense1</sub> (mV)	V <sub>sense2</sub> (mV)
50	50	5
100	40	5

Parameter definitions TSC1031

#### 4.4 Output voltage drift versus temperature

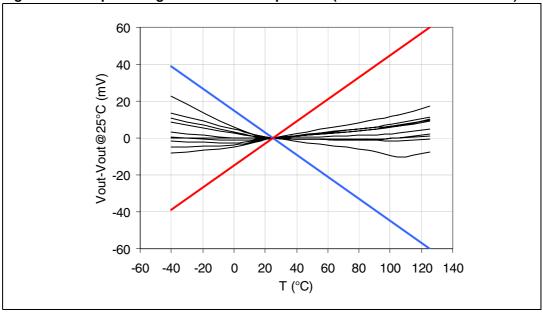
The output voltage drift versus temperature is defined as the maximum variation of  $V_{out}$  with respect to its value at 25° C over the temperature range. It is calculated as follows:

$$\frac{\Delta V_{out}}{\Delta T} = max \frac{V_{out}(T_{amb}) - V_{out}(25^{\circ}C)}{T_{amb} - 25^{\circ}C}$$

with  $T_{min} < T_{amb} < T_{max}$ .

Figure 5 provides a graphical definition of the output voltage drift versus temperature. On this chart  $V_{out}$  is always comprised in the area defined by the maximum and minimum variation of  $V_{out}$  versus T, and T = 25° C is considered to be the reference.





TSC1031 Parameter definitions

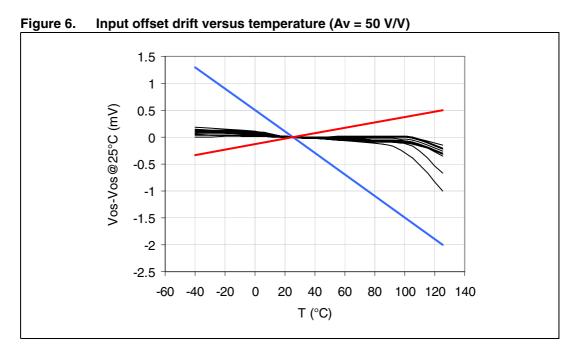
#### 4.5 Input offset drift versus temperature

The input voltage drift versus temperature is defined as the maximum variation of  $V_{os}$  with respect to its value at 25° C over the temperature range. It is calculated as follows:

$$\frac{\Delta V_{os}}{\Delta T} = max \frac{V_{os}(T_{amb}) - V_{os}(25^{\circ}C)}{T_{amb} - 25^{\circ}C}$$

with  $T_{min} < T_{amb} < T_{max}$ .

Figure 6. provides a graphical definition of the input offset drift versus temperature. On this chart  $V_{os}$  is always comprised in the area defined by the maximum and minimum variation of  $V_{os}$  versus T, and T = 25° C is considered to be the reference.



### 4.6 Output voltage accuracy

The output voltage accuracy is the difference between the actual output voltage and the theoretical output voltage. Ideally, the current sensing output voltage should be equal to the input differential voltage multiplied by the theoretical gain, as in the following formula.

$$V_{out-th} = Av . V_{sense}$$

The actual value is very slightly different, mainly due to the effects of:

- the input offset voltage V<sub>os</sub>,
- the non-linearity.

Parameter definitions TSC1031

Vout
Actual
Ideal

Vout accuracy for Vsense = 5 mV

Vsense

5 mV

AM04521

Figure 7. Vout vs. Vsense theoretical and actual characteristics

The output voltage accuracy, expressed as a percentage, can be calculated with the following formula,

$$\Delta V_{out} = \frac{abs(V_{out} - (Av \cdot V_{sense}))}{Av \cdot V_{sense}}$$

with 50 V/V or 100 V/V depending on the configuration of the SEL and SEL2 pins.

### 5 Maximum permissible voltages on pins

The TSC1031 can be used in either single- or dual-supply configuration. The dual-supply configuration is achieved by disconnecting Vcc- and Gnd, and connecting Vcc- to a negative supply. *Figure 8* illustrates how the absolute maximum voltages on input pins Vp and Vm are referred to the Vcc- potential, while the maximum voltages on the positive supply pin, gain selection pins and output pins are referred to the Gnd pin. It should also be noted that the maximum voltage between Vcc- and Vcc+ is limited to 15 V.

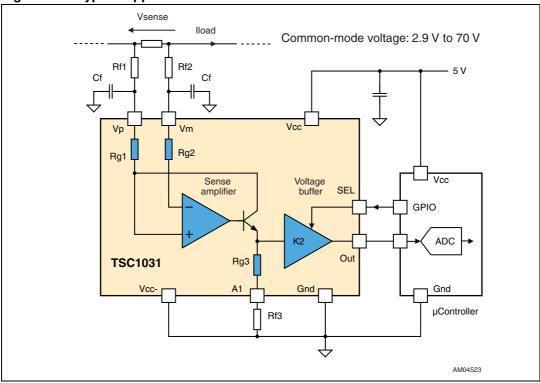
Vp and Vm SEL and Out Vcc+ Vcc+ + 0.3 V+15 V Gnd -0.3V -0.3 V Vcc+ SEL and Out Vcc-Vcc--16 V Vp and Vm AM04528

Figure 8. Maximum voltages on pins

### 6 Application information

The TSC1031 can be used to measure current and to feed back the information to a microcontroller.

Figure 9. Typical application



The current from the supply flows to the load through the  $R_{sense}$  resistor causing a voltage drop equal to  $V_{sense}$  across  $R_{sense}$ . The amplifier's input currents are negligible, therefore its inverting input voltage is equal to  $V_m$ . The amplifier's open-loop gain forces its non-inverting input to the same voltage as the inverting input. As a consequence, the amplifier adjusts current flowing through Rg1 so that the voltage drop across Rg1 exactly matches  $V_{sense}$ .

Therefore, the drop across Rg1 is:

$$V_{Rg1} = V_{sense} = R_{sense} I_{load}$$

If  $I_{Rq1}$  is the current flowing through Rg1, then  $I_{Rq1}$  is given by the formula:

$$I_{Rg1} = V_{sense}/Rg1$$

The  $I_{Rg1}$  current flows entirely into resistor  $R_{g3}$  (the input bias current of the buffer is negligible). Therefore, the voltage drop on the  $R_{g3}$  resistor can be calculated as follows.

$$V_{Rg3} = R_{g3}.I_{Rg1} = (R_{g3}/R_{g1}).V_{sense}$$

Since the voltage across the  $R_{g3}$  resistor is buffered to the Out pin,  $V_{out}$  can be expressed as:

$$V_{out} = (R_{q3}/R_{q1}).V_{sense}$$

or:

$$V_{out} = (R_{g3}/R_{g1}).R_{sense}.I_{load}$$

The resistor ratio  $R_{g3}/R_{g1}$  is internally set to 20 V/V for TSC1031. Since they define the full-scale output range of the application, the  $R_{sense}$  resistor and the  $R_{g3}/R_{g1}$  resistor ratio (equal to Av) are important parameters and must therefore be selected carefully.

The TSC1031's dedicated schematic eases the implementation of EMI filtering in harsh environments. An example of filters is described in *Figure 9*, where the input filtering is performed by  $R_{f1}$ ,  $R_{f2}$  and  $C_{f}$ .

The values of  $R_{f1}$  and  $R_{f2}$  should be equal so as to balance the contribution on both amplifier inputs. The value of the  $C_f$  capacitor should be chosen so that the cut-off frequency of the first-order low-pass filter provides enough attenuation to the high frequency interferences.

To balance the contribution of  $R_{f1}$  and  $R_{f2}$  in the current sense amplifier gain, an output resistor  $R_{f3}$  should be connected between pin A1 and Gnd. The value of  $R_{f3}$  should be chosen according to the following formula.

$$K1 = 25 = R_{q3}/R_{q1} = R_{f3}/R_{f1}$$

These precautions having been taken, the TSC1031's gain will be unaffected by the implementation of the input filtering resistors.

Package information TSC1031

# 7 Package information

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK<sup>®</sup> packages, depending on their level of environmental compliance. ECOPACK<sup>®</sup> specifications, grade definitions and product status are available at: <a href="https://www.st.com">www.st.com</a>. ECOPACK<sup>®</sup> is an ST trademark.

# 7.1 SO-8 package information

Figure 10. SO-8 package mechanical drawing

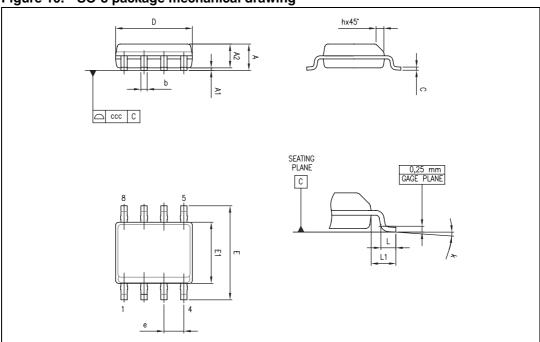


Table 10. SO-8 package mechanical data

			Dime	nsions		
Ref.		Millimeters			Inches	
	Min.	Тур.	Max.	Min.	Тур.	Max.
Α			1.75			0.069
A1	0.10		0.25	0.004		0.010
A2	1.25			0.049		
b	0.28		0.48	0.011		0.019
С	0.17		0.23	0.007		0.010
D	4.80	4.90	5.00	0.189	0.193	0.197
E	5.80	6.00	6.20	0.228	0.236	0.244
E1	3.80	3.90	4.00	0.150	0.154	0.157
е		1.27			0.050	
h	0.25		0.50	0.010		0.020
L	0.40		1.27	0.016		0.050
L1		1.04			0.040	
k	0		8°	1°		8°
CCC			0.10			0.004

Package information TSC1031

## 7.2 TSSOP-8 package information

Figure 11. TSSOP8 package mechanical drawing

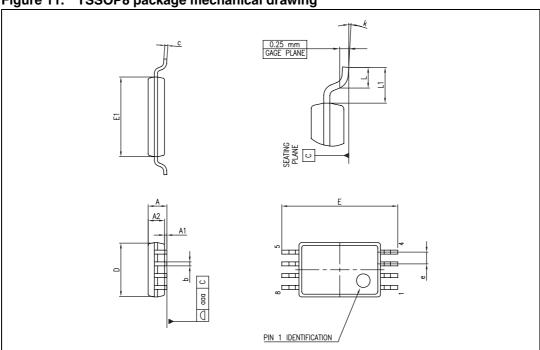


Table 11. TSSOP8 package mechanical data

	Dimensions								
Ref.	Millimeters			Inches					
	Min.	Тур.	Max.	Min.	Тур.	Max.			
Α			1.20			0.047			
A1	0.05		0.15	0.002		0.006			
A2	0.80	1.00	1.05	0.031	0.039	0.041			
b	0.19		0.30	0.007		0.012			
С	0.09		0.20	0.004		0.008			
D	2.90	3.00	3.10	0.114	0.118	0.122			
E	6.20	6.40	6.60	0.244	0.252	0.260			
E1	4.30	4.40	4.50	0.169	0.173	0.177			
е		0.65			0.0256				
k	0°		8°	0°		8°			
L	0.45	0.60	0.75	0.018	0.024	0.030			
L1		1			0.039				
aaa			0.10			0.004			

# 8 Ordering information

Table 12. Order codes

Part number	Temperature range	Package	Packaging	Marking
TSC1031IPT	-40°C, +125°C	TSSOP8	Tape & reel	10311
TSC1031IDT	-40 C, +125 C	SO-8	Tape & reel	TSC1031I
TSC1031IYPT <sup>(1)</sup>	-40°C, +125°C	TSSOP8	Tape & reel	1031Y
TSC1031IYDT	Automotive grade	SO-8	Tape & reel	TSC1031Y

Qualification and characterization according to AEC Q100 and Q003 or equivalent, advanced screening according to AEC Q001 & Q002 or equivalent are on-going.

Revision history TSC1031

# 9 Revision history

Table 13. Document revision history

Date	Revision	Changes
04-Jan-2010	1	Initial release.

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