

TDA4864J; TDA4864AJ

Vertical deflection booster

Rev. 01 — 12 August 2004

Product data sheet

1. General description

The TDA4864J and TDA4864AJ are deflection boosters for use in vertical deflection systems for frame frequencies up to 200 Hz.

The TDA4864J needs a separate flyback supply voltage, so the supply voltages are independently adjustable to optimize power consumption and flyback time.

For the TDA4864AJ the flyback supply voltage will be generated internally by doubling the supply voltage and therefore a separate flyback supply voltage is not needed.

Both circuits provide differential input stages.

2. Features

- Power amplifier with differential inputs
- Output current up to 2.5 A (p-p)
- High vertical deflection frequency up to 200 Hz
- High linear sawtooth signal amplification
- Flyback generator:
 - ◆ TDA4864J: separate adjustable flyback supply voltage up to 60 V
 - ◆ TDA4864AJ: internally doubled supply voltage (two supply voltages only for DC-coupled outputs).

3. Quick reference data

Table 1: Quick reference data
Measurements referenced to pin GND.

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|----------|---|----------------------|--------------|-----|----------------|------|
| V_{P1} | supply voltage 1 | | 9 | - | 30 | V |
| V_{P2} | supply voltage 2 for vertical output | | $V_{P1} - 1$ | - | 60 | V |
| V_{FB} | flyback supply voltage of TDA4864J | | $V_{P1} - 1$ | - | 60 | V |
| V_{P3} | flyback generator output voltage of TDA4864AJ | $I_{VOUT} = -1.25$ A | 0 | - | $V_{P1} + 2.2$ | V |
| V_i | input voltage on | | | | | |
| | pin INN | | 1.6 | - | $V_{P1} - 0.5$ | V |
| | pin INP | | 1.6 | - | $V_{P1} - 0.5$ | V |
| I_{P1} | supply current 1 | during scan | - | 6 | 10 | mA |

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Table 1: Quick reference data ...continued
Measurements referenced to pin GND.

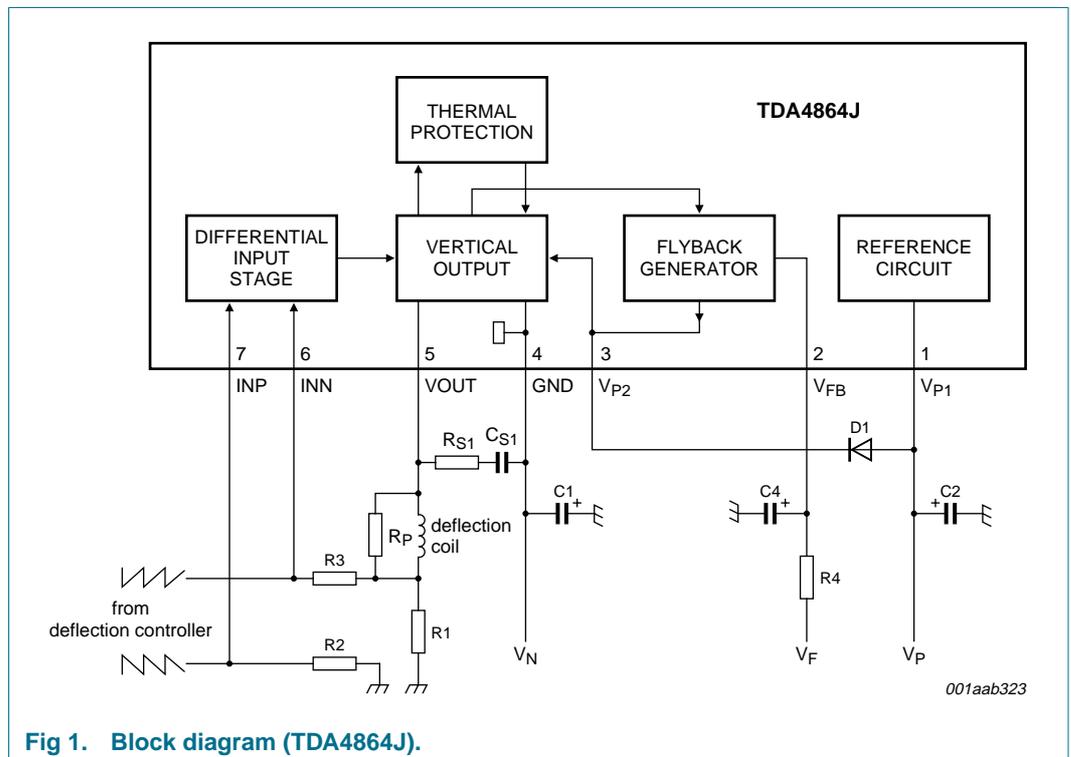
| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|-----------------|---|----------------|-----|-----|-----|------|
| I_{P2} | quiescent supply current 2 | $I_{VOUT} = 0$ | - | 25 | 60 | mA |
| $I_{VOUT(p-p)}$ | vertical deflection output current (peak-to-peak value) | | - | - | 2.5 | A |
| T_{amb} | ambient temperature | | -20 | - | +75 | °C |

4. Ordering information

Table 2: Ordering information

| Type number | Package | | Version |
|-------------|---------|---|----------|
| | Name | Description | |
| TDA4864J | DBS7P | plastic DIL-bent-SIL power package; 7 leads | SOT524-1 |
| TDA4864AJ | | (lead length 12/11 mm); exposed die pad | |

5. Block diagram



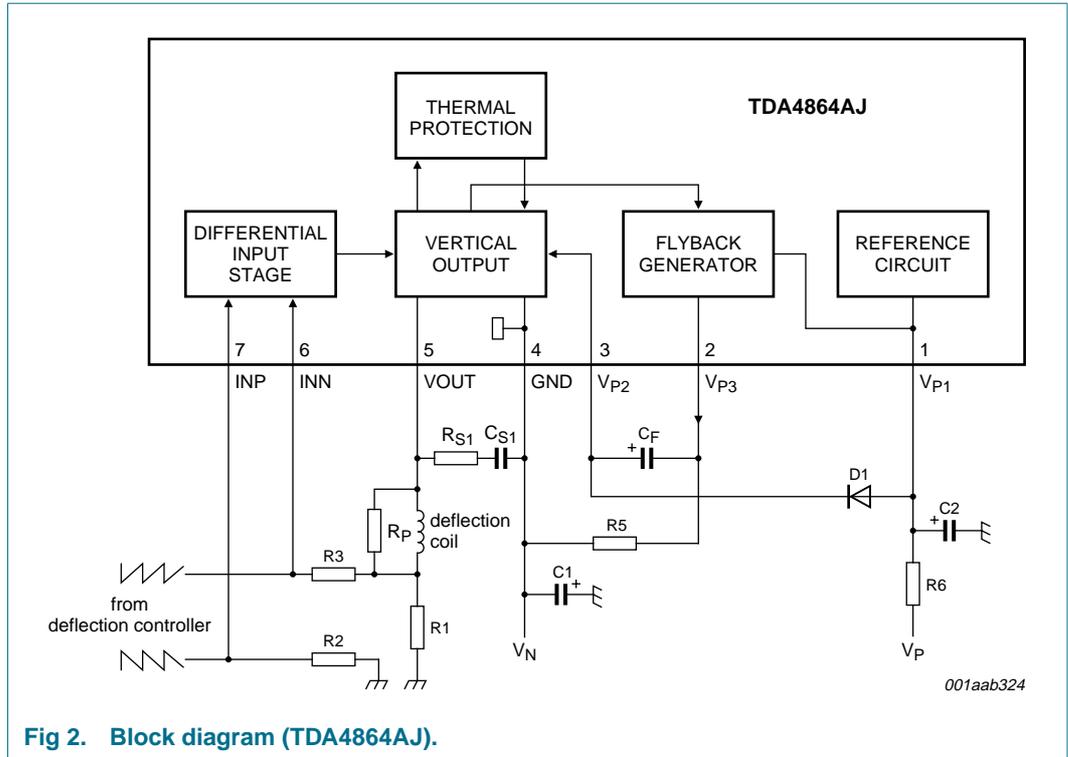
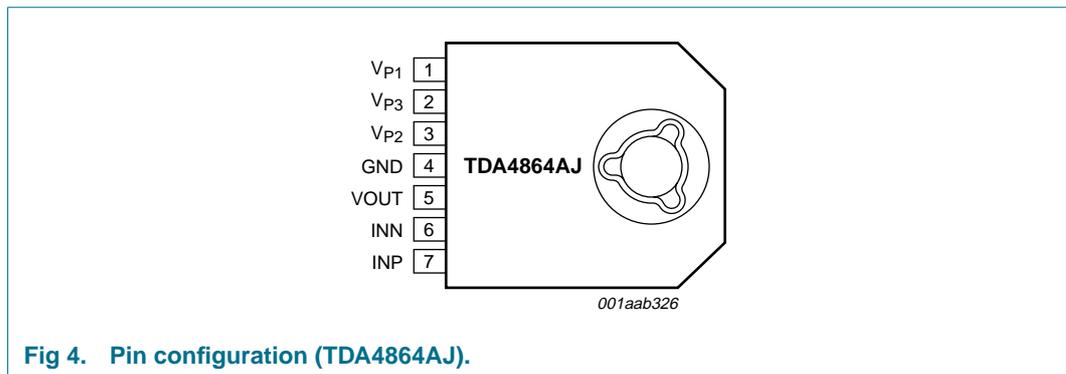
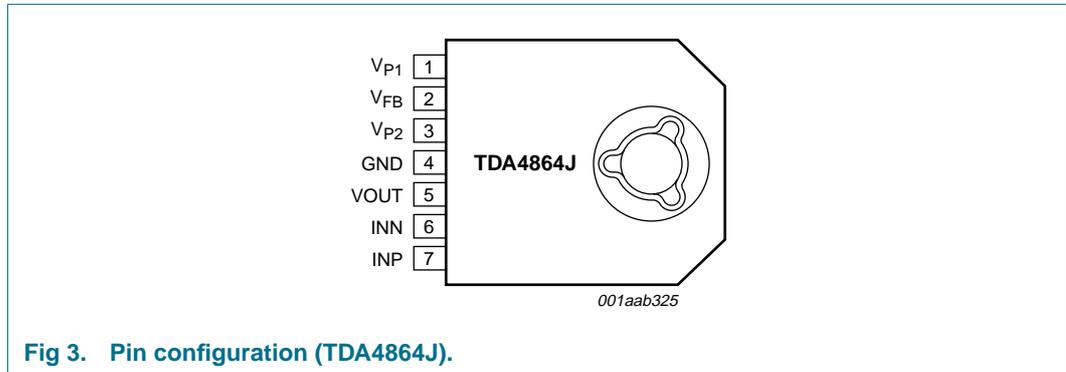


Fig 2. Block diagram (TDA4864AJ).

6. Pinning information

6.1 Pinning



6.2 Pin description

Table 3: Pin description

| Symbol | Pin | | Description |
|------------------|----------|-----------|--|
| | TDA4864J | TDA4864AJ | |
| V _{P1} | 1 | 1 | positive supply voltage 1 |
| V _{FB} | 2 | - | flyback supply voltage |
| V _{P3} | - | 2 | flyback generator output |
| V _{P2} | 3 | 3 | supply voltage 2 for vertical output |
| GND | 4 | 4 | ground or negative supply voltage |
| V _{OUT} | 5 | 5 | vertical output |
| INN | 6 | 6 | inverted input of differential input stage |
| INP | 7 | 7 | non-inverted input of differential input stage |

7. Functional description

Both the TDA4864J and TDA4864AJ consist of a differential input stage, a vertical output stage, a flyback generator, a reference circuit and a thermal protection circuit.

The TDA4864J operates with a separate flyback supply voltage (see [Figure 1](#)) while the TDA4864AJ generates the flyback voltage internally by doubling the supply voltage (see [Figure 2](#)).

7.1 Differential input stage

The differential sawtooth input current signal (from the deflection controller) is connected to the inputs (inverted signal to pin INN and non-inverted signal to pin INP). The vertical feedback signal is superimposed on the inverted signal on pin INN.

7.2 Vertical output and thermal protection

The vertical output stage is a quasi-complementary class-B amplifier with a high linearity.

The output stage is protected against thermal overshoots. For a junction temperature of $T_j > 150\text{ }^\circ\text{C}$ the protection will be activated and will reduce the deflection current (I_{VOUT}).

7.3 Flyback generator

The flyback generator supplies the vertical output stage during flyback.

The TDA4864J is used with a separate flyback supply voltage to achieve a short flyback time with minimized power dissipation.

The TDA4864AJ needs a capacitor (C_F) connected between pins V_{P3} and V_{P2} (see [Figure 2](#)). Capacitor C_F is charged during scan, using the external diode D1 and resistor R5. During flyback the cathode of capacitor C_F is connected to the positive supply voltage and the flyback voltage is then twice the supply voltage. For the TDA4864AJ the resistor R6 in the positive supply line can be used to reduce the power consumption.

In parallel with the deflection coil a damping resistor R_P and an RC combination ($R_{S1} = 5.6\ \Omega$ and $C_{S1} = 100\ \text{nF}$) are needed. Furthermore, another additional RC combination ($R_{S2} = 5.6\ \Omega$ and $C_{S2} = 47\ \text{nF}$ to $150\ \text{nF}$) can be used to minimize the noise effect and the flyback time (see [Figure 7](#) and [8](#)).

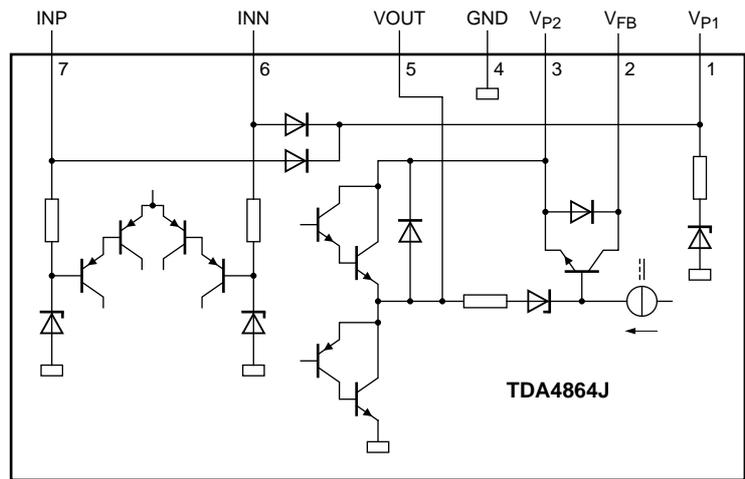
8. Internal circuitry

Table 4: Internal circuitry

| Pin | Symbol | Internal circuits |
|-----|--------|-------------------|
|-----|--------|-------------------|

TDA4864J

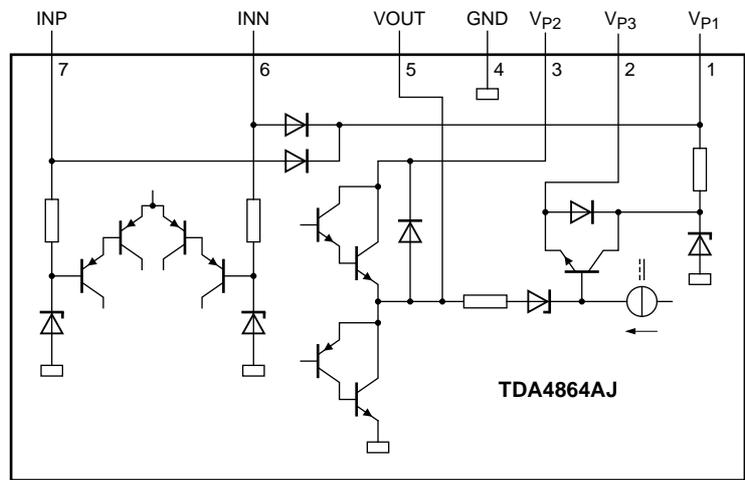
| | |
|---|----------|
| 1 | V_{P1} |
| 2 | V_{FB} |
| 3 | V_{P2} |
| 4 | GND |
| 5 | VOUT |
| 6 | INN |
| 7 | INP |



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TDA4864AJ

| | |
|---|----------|
| 1 | V_{P1} |
| 2 | V_{P3} |
| 3 | V_{P2} |
| 4 | GND |
| 5 | VOUT |
| 6 | INN |
| 7 | INP |



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9. Limiting values

Table 5: Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages referenced to pin GND; unless otherwise specified.

| Symbol | Parameter | Conditions | Min | Max | Unit |
|---------------|---|------------|------|--------------|------|
| V_{P1} | supply voltage 1 | | - | 40 | V |
| V_{P2} | supply voltage 2 | | - | 60 | V |
| V_{FB} | flyback supply voltage of TDA4864J | | - | 60 | V |
| V_{P3} | flyback generator output voltage of TDA4864AJ | | 0 | $V_{P1} + 3$ | V |
| V_i | input voltage on | | | | |
| | pin INN | | - | V_{P1} | V |
| | pin INP | | - | V_{P1} | V |
| $V_{O(VOUT)}$ | output voltage on pin VOUT | | - | 62 | V |
| I_{P2} | supply current 2 | | - | ± 1.5 | A |
| $I_{O(VOUT)}$ | output current on pin VOUT | [1] | - | ± 1.5 | A |
| I_{VFB} | current during flyback of TDA4864J | | - | ± 1.5 | A |
| I_{VP3} | current during flyback of TDA4864AJ | | - | ± 1.5 | A |
| T_{stg} | storage temperature | | -25 | +150 | °C |
| T_{amb} | ambient temperature | | -20 | +75 | °C |
| T_j | junction temperature | [1] | - | 150 | °C |
| V_{esd} | electrostatic discharge voltage on all pins | [2] | -300 | +300 | V |

[1] Internally limited by thermal protection; will be activated for $T_j \geq 150$ °C.

[2] Equivalent to discharging a 200 pF capacitor through a 0 Ω series resistor.

10. Thermal characteristics

Table 6: Thermal characteristics

| Symbol | Parameter | Conditions | Typ | Unit |
|----------------|---|------------|-------|------|
| $R_{th(j-mb)}$ | thermal resistance from junction to mounting base | | [1] 6 | K/W |

[1] To minimize the thermal resistance from mounting base to heatsink [$R_{th(mb-h)}$] follow the recommended mounting instruction: screw mounting preferred; torque = 40 Ncm; use heatsink compound; isolation plate increases $R_{th(mb-h)}$.

11. Characteristics

Table 7: Characteristics
 $V_{P1} = 25\text{ V}$; $T_{amb} = 25\text{ }^{\circ}\text{C}$; voltages referenced to pin GND; unless otherwise specified.

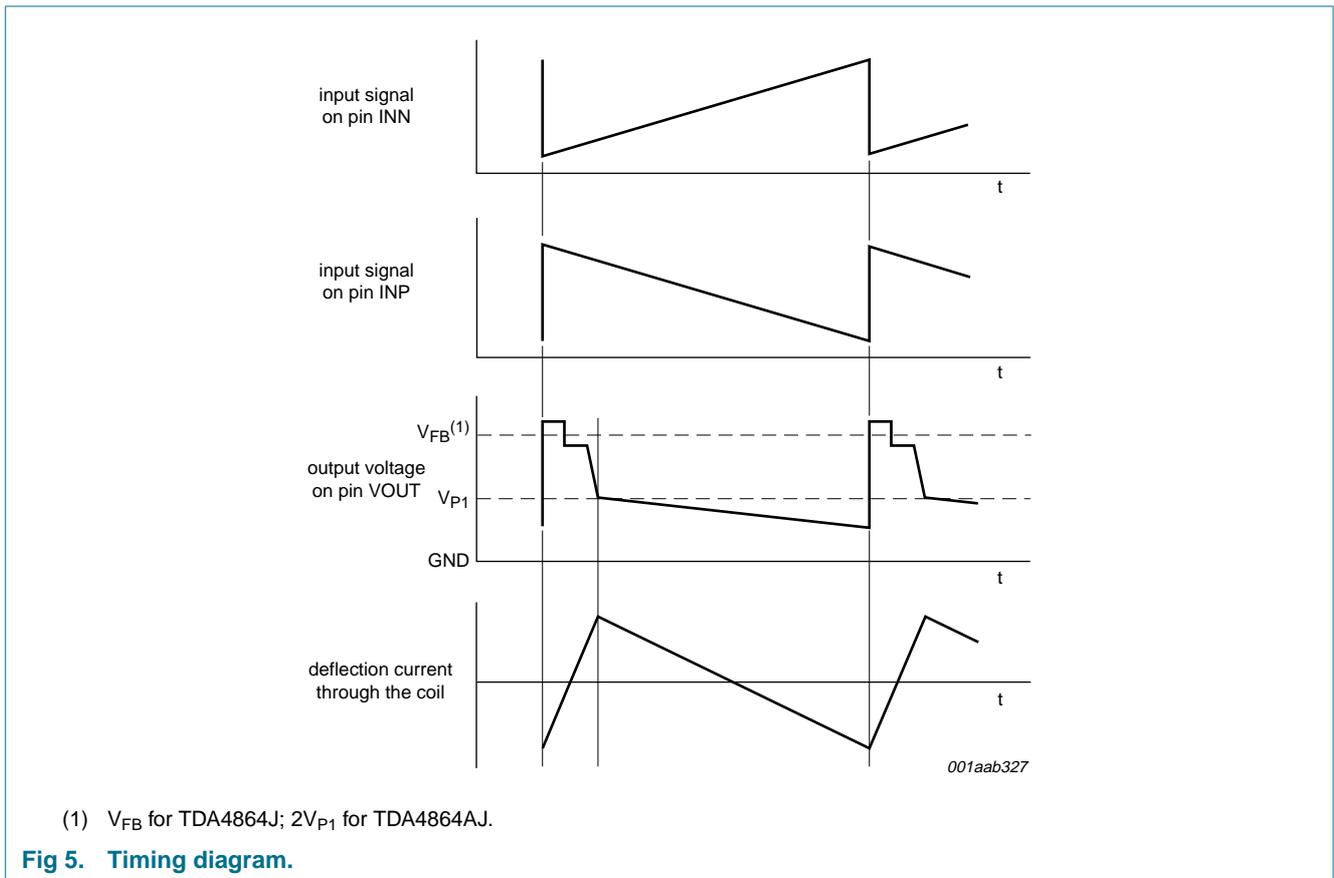
| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|--|---|-----------------------------|--------------|------|----------------|------|
| Supplies | | | | | | |
| V_{P1} | supply voltage 1 | | 9 | - | 30 | V |
| V_{P2} | supply voltage 2 | | $V_{P1} - 1$ | - | 60 | V |
| V_{FB} | flyback supply voltage of TDA4864J | | $V_{P1} - 1$ | - | 60 | V |
| V_{P3} | flyback generator output voltage of TDA4864AJ | $I_{VOUT} = -1.25\text{ A}$ | 0 | - | $V_{P1} + 2.2$ | V |
| I_{P1} | supply current 1 | during scan | - | 6 | 10 | mA |
| I_{P2} | quiescent supply current 2 | $I_{VOUT} = 0$ | - | 25 | 60 | mA |
| Differential input stage | | | | | | |
| V_i | input voltage on | | | | | |
| | pin INN | | 1.6 | - | $V_{P1} - 0.5$ | V |
| | pin INP | | 1.6 | - | $V_{P1} - 0.5$ | V |
| I_q | input quiescent current on | | | | | |
| | pin INN | | - | -100 | -500 | nA |
| | pin INP | | - | -100 | -500 | nA |
| Flyback generator | | | | | | |
| I_{VFB} | current during flyback of TDA4864J | | - | - | ± 1.5 | A |
| I_{VP3} | current during flyback of TDA4864AJ | | - | - | ± 1.5 | A |
| $V_{VP2-VFB}$ | voltage drop during flyback of TDA4864J | | | | | |
| | reverse | $I_{VOUT} = -1\text{ A}$ | - | -1.5 | - | V |
| | | $I_{VOUT} = -1.25\text{ A}$ | - | -2 | - | V |
| | forward | $I_{VOUT} = 1\text{ A}$ | - | 2.2 | - | V |
| | | $I_{VOUT} = 1.25\text{ A}$ | - | 2.5 | - | V |
| $V_{VP3-VP1}$ | voltage drop during flyback of TDA4864AJ | | | | | |
| | reverse | $I_{VOUT} = -1\text{ A}$ | - | -1.5 | - | V |
| | | $I_{VOUT} = -1.25\text{ A}$ | - | -2 | - | V |
| | forward | $I_{VOUT} = 1\text{ A}$ | - | 2.2 | - | V |
| | | $I_{VOUT} = 1.25\text{ A}$ | - | 2.5 | - | V |
| Vertical output stage; see Figure 5 | | | | | | |
| I_{VOUT} | vertical deflection output current | | - | - | ± 1.25 | A |
| $I_{VOUT(p-p)}$ | vertical deflection output current (peak-to-peak value) | | - | - | 2.5 | A |
| $V_{o(sat)n}$ | output saturation voltage to ground | $I_{VOUT} = 1\text{ A}$ | - | 1.4 | 1.7 | V |
| | | $I_{VOUT} = 1.25\text{ A}$ | - | 1.8 | 2.3 | V |

Table 7: Characteristics ...continued

$V_{P1} = 25\text{ V}$; $T_{amb} = 25\text{ }^\circ\text{C}$; voltages referenced to pin GND; unless otherwise specified.

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|---------------|---------------------------------------|----------------------------|------|------|-----|------|
| $V_{o(sat)p}$ | output saturation voltage to V_{P2} | $I_{VOUT} = 1\text{ A}$ | -2.3 | -2 | - | V |
| | | $I_{VOUT} = 1.25\text{ A}$ | -2.8 | -2.3 | - | V |
| LIN | non-linearity of output signal | | [1] | - | 1 | % |

[1] Deviation of the output slope at a constant input slope.



12. Application information

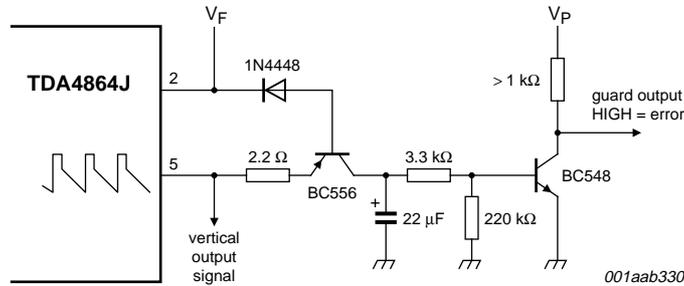
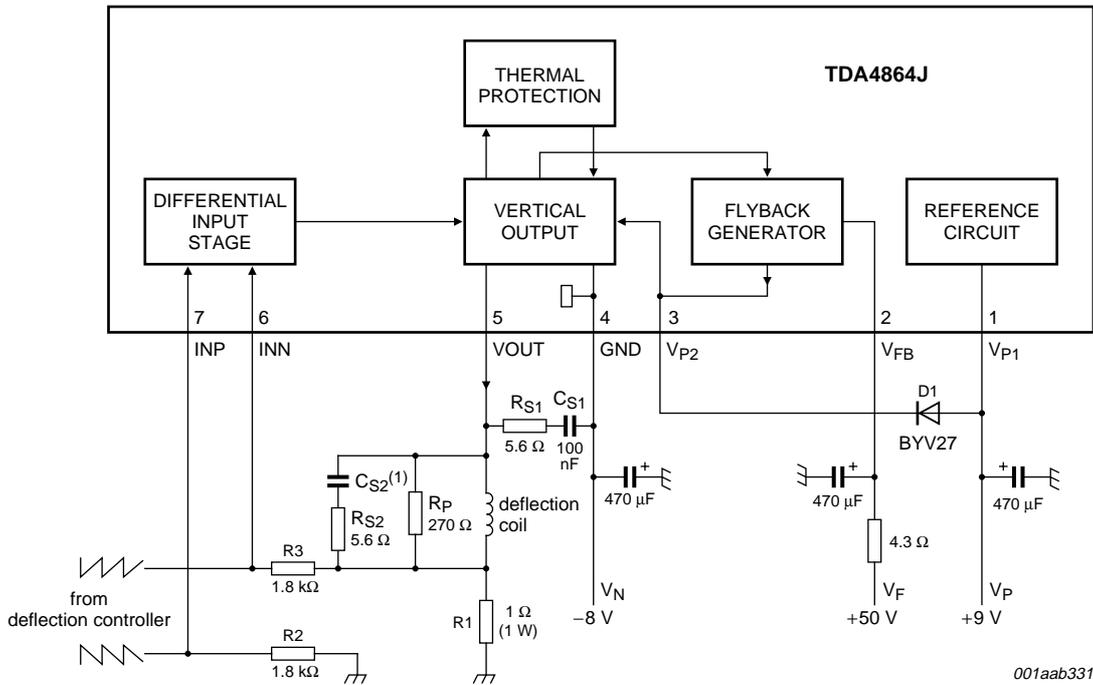


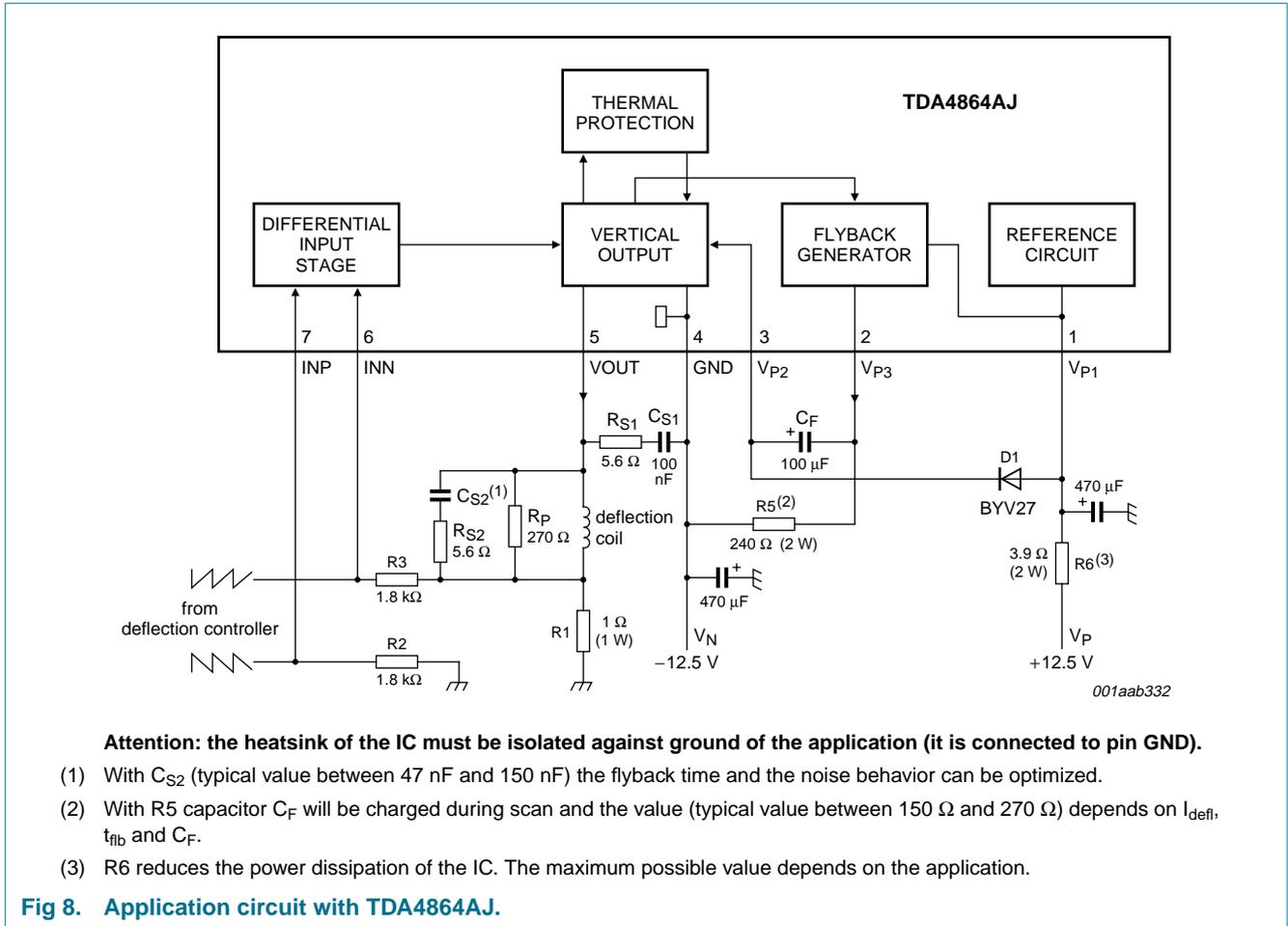
Fig 6. Application circuit with TDA4864J for external guard signal generation.



Attention: the heatsink of the IC must be isolated against ground of the application (it is connected to pin GND).

(1) With C_{S2} (typical value between 47 nF and 150 nF) the flyback time and the noise behavior can be optimized.

Fig 7. Application circuit with TDA4864J.



12.1 Example for both TDA4864J and TDA4864AJ

Table 8: Values given from application

| Symbol | Value | Unit |
|------------------|-------|------|
| $I_{defl(max)}$ | 0.71 | A |
| $L_{defcoil}$ | 6 | mH |
| $R_{defcoil}$ | 6 | Ω |
| R_P | 270 | Ω |
| R1 | 1 | Ω |
| R2 | 1.8 | kΩ |
| R3 | 1.8 | kΩ |
| V_{FB} [1] | 50 | V |
| T_{amb} | 60 | °C |
| $T_{defcoil}$ | 75 | °C |
| $R_{th(j-mb)}$ | 6 | K/W |
| $R_{th(mb-amb)}$ | 8 | K/W |

[1] For TDA4864J only.

Table 9: Calculated values

| Symbol | Value | | Unit |
|---------------|----------|-----------|------|
| | TDA4864J | TDA4864AJ | |
| V_{P1} | 9 | 12.5 | V |
| V_N | -8 | -12.5 | V |
| P_{tot} | 3.2 | 4.4 | W |
| P_{defl} | 1.2 | 1.2 | W |
| P_{IC} | 2 | 3.2 | W |
| $R_{th(tot)}$ | 14 | 14 | K/W |
| $T_{j(max)}$ | 88 | 105 | °C |

V_{P1} , V_N and V_{FB} are referenced to ground of application; voltages are calculated with +10 % tolerances.

The calculation formulae for supply voltages are as follows:

$$V_{P1} = -V_{o(sat)p} + (R1 + R_{deflcoil}) \times I_{defl(max)} - U'_L + U_{D1}$$

$$V_N = V_{o(sat)n} + (R1 + R_{deflcoil}) \times I_{defl(max)} + U'_L$$

where:

$$U'_L = L_{deflcoil} \times 2I_{defl(max)} \times f_v$$

f_v = vertical deflection frequency

U_{D1} = forward voltage drop across D1.

The calculation formulae for power consumption is:

$$P_{IC} = P_{tot} - P_{defl}$$

$$P_{tot} = (V_{P1} - U_{D1}) \times \frac{I_{defl(max)}}{4} + V_N \times \frac{I_{defl(max)}}{4} + (V_{P1} - V_N) \times 0.01 \text{ A} + 0.2 \text{ W}$$

$$P_{defl} = \frac{R_{deflcoil} + R1}{3} \times I_{defl(max)}^2$$

where:

P_{IC} = power dissipation of the IC

P_{tot} = total power dissipation

P_{defl} = power dissipation of the deflection coil.

Calculation formulae for maximum required thermal resistance for the heatsink at

$T_{j(max)} = 110 \text{ °C}$:

$$R_{th(mb-amb)} = \left(\frac{T_{j(max)} - T_{amb}}{P_{IC}} \right) - R_{th(j-mb)} = 19 \text{ K/W (max.)}$$

Table 10: t_{flb} as a function of V_{FB} for TDA4864J

| t_{flb} (μs) | V_{FB} (V) |
|------------------------------------|---------------------|
| 350 | 30 |
| 250 | 40 |
| 210 | 50 |

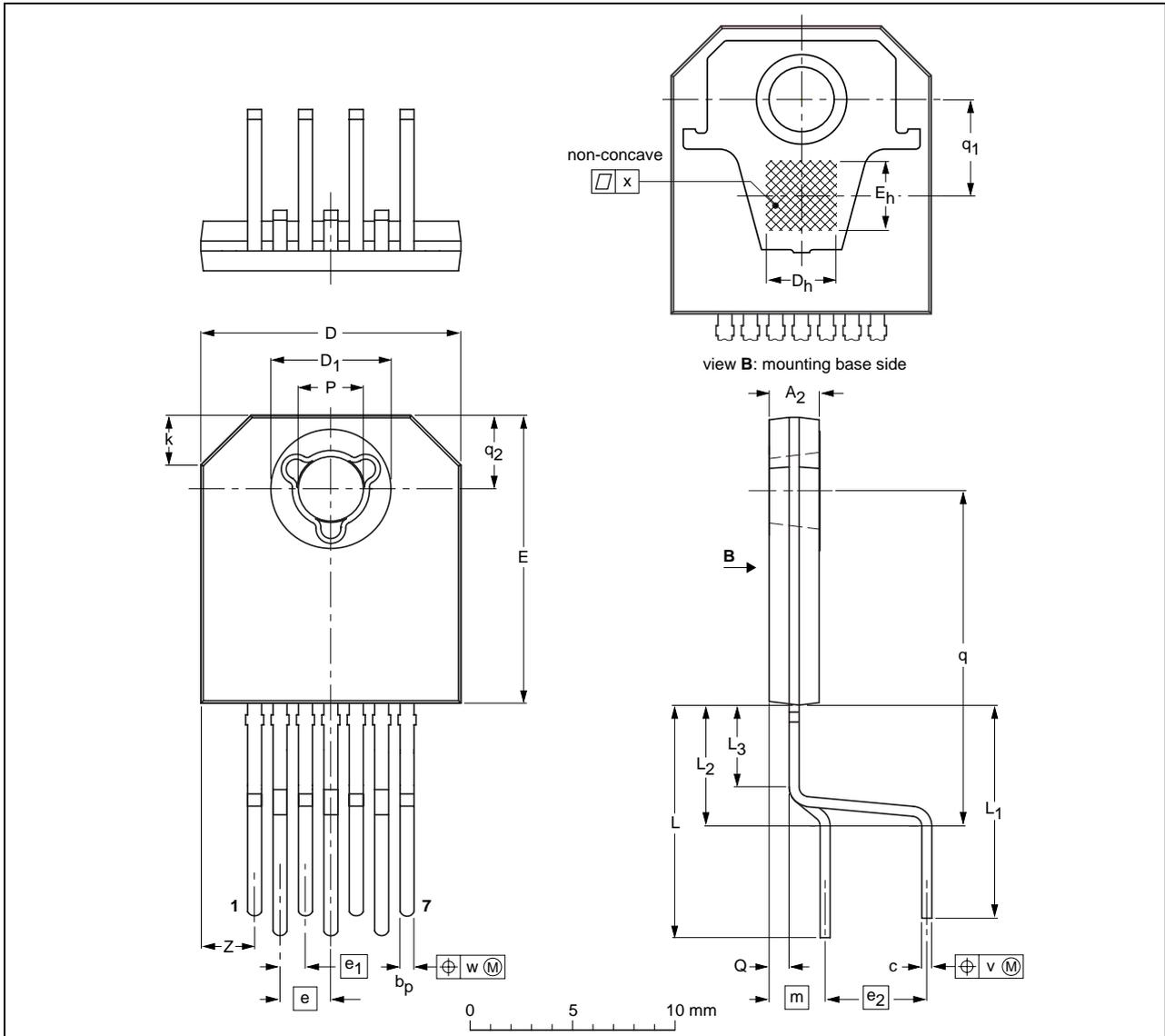
Table 11: t_{flb} as a function of V_{P1} and V_{N} for TDA4864AJ

| t_{flb} (μs) | V_{P1} (V) | V_{N} (V) | P_{IC} (W) | R_6 (Ω) |
|------------------------------------|---------------------|--------------------|---------------------|--------------------|
| 360 | +10 | -10 | +2.5 | +1 |
| 290 | +12.5 | -12.5 | +3.2 | +3.9 |
| 240 | +15 | -15 | +3.9 | +6.8 |

13. Package outline

DBS7P: plastic DIL-bent-SIL power package; 7 leads (lead length 12/11 mm); exposed die pad SOT524-1

SOT524-1



DIMENSIONS (mm are the original dimensions)

| UNIT | A ₂ ⁽²⁾ | b _p | c | D ⁽¹⁾ | D ₁ ⁽²⁾ | D _h | E ⁽¹⁾ | E _h | e | e ₁ | e ₂ | k | L | L ₁ | L ₂ | L ₃ | m | P | Q | q | q ₁ | q ₂ | v | w | x | Z ⁽¹⁾ |
|------|-------------------------------|----------------|--------------|------------------|-------------------------------|----------------|------------------|----------------|------|----------------|----------------|--------|--------------|----------------|----------------|----------------|-----|------------|--------------|--------------|----------------|----------------|-----|-----|------|------------------|
| mm | 2.7 2.3 | 0.80 0.65 | 0.58 0.48 | 13.2 12.8 | 6.2 5.8 | 3.5 | 14.7 14.3 | 3.5 | 2.54 | 1.27 | 5.08 | 3 2 | 12.4 11.0 | 11.4 10.0 | 6.7 5.5 | 4.5 3.7 | 2.8 | 3.4 3.1 | 1.15 0.85 | 17.5 16.3 | 4.85 | 3.8 3.6 | 0.8 | 0.3 | 0.02 | 2.92 2.37 |

Notes

1. Plastic or metal protrusions of 0.25 mm maximum per side are not included.
2. Plastic surface within circle area D₁ may protrude 0.04 mm maximum.

| OUTLINE VERSION | REFERENCES | | | | EUROPEAN PROJECTION | ISSUE DATE |
|-----------------|------------|-------|-------|--|---------------------|-----------------------|
| | IEC | JEDEC | JEITA | | | |
| SOT524-1 | | | | | | 00-07-03- 03-03-12 |

Fig 9. Package outline.

14. Soldering

14.1 Introduction to soldering through-hole mount packages

This text gives a brief insight to wave, dip and manual soldering. A more in-depth account of soldering ICs can be found in our *Data Handbook IC26; Integrated Circuit Packages* (document order number 9398 652 90011).

Wave soldering is the preferred method for mounting of through-hole mount IC packages on a printed-circuit board.

14.2 Soldering by dipping or by solder wave

Driven by legislation and environmental forces the worldwide use of lead-free solder pastes is increasing. Typical dwell time of the leads in the wave ranges from 3 seconds to 4 seconds at 250 °C or 265 °C, depending on solder material applied, SnPb or Pb-free respectively.

The total contact time of successive solder waves must not exceed 5 seconds.

The device may be mounted up to the seating plane, but the temperature of the plastic body must not exceed the specified maximum storage temperature ($T_{stg(max)}$). If the printed-circuit board has been pre-heated, forced cooling may be necessary immediately after soldering to keep the temperature within the permissible limit.

14.3 Manual soldering

Apply the soldering iron (24 V or less) to the lead(s) of the package, either below the seating plane or not more than 2 mm above it. If the temperature of the soldering iron bit is less than 300 °C it may remain in contact for up to 10 seconds. If the bit temperature is between 300 °C and 400 °C, contact may be up to 5 seconds.

14.4 Package related soldering information

Table 12: Suitability of through-hole mount IC packages for dipping and wave soldering methods

| Package | Soldering method | |
|---------------------------------|------------------|------------------------------|
| | Dipping | Wave |
| CPGA, HCPGA | – | suitable |
| DBS, DIP, HDIP, RDBS, SDIP, SIL | suitable | suitable [1] |
| PMFP [2] | – | not suitable |

[1] For SDIP packages, the longitudinal axis must be parallel to the transport direction of the printed-circuit board.

[2] For PMFP packages hot bar soldering or manual soldering is suitable.

15. Revision history

Table 13: Revision history

| Document ID | Release date | Data sheet status | Change notice | Order number | Supersedes |
|----------------------|--------------|--------------------|---------------|----------------|------------|
| TDA4864J_TDA4864AJ_1 | 20040812 | Product data sheet | - | 9397 750 13441 | - |

16. Data sheet status

| Level | Data sheet status ^[1] | Product status ^[2] ^[3] | Definition |
|-------|----------------------------------|--|--|
| I | Objective data | Development | This data sheet contains data from the objective specification for product development. Philips Semiconductors reserves the right to change the specification in any manner without notice. |
| II | Preliminary data | Qualification | This data sheet contains data from the preliminary specification. Supplementary data will be published at a later date. Philips Semiconductors reserves the right to change the specification without notice, in order to improve the design and supply the best possible product. |
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[2] The product status of the device(s) described in this data sheet may have changed since this data sheet was published. The latest information is available on the Internet at URL <http://www.semiconductors.philips.com>.

[3] For data sheets describing multiple type numbers, the highest-level product status determines the data sheet status.

17. Definitions

Short-form specification — The data in a short-form specification is extracted from a full data sheet with the same type number and title. For detailed information see the relevant data sheet or data handbook.

Limiting values definition — Limiting values given are in accordance with the Absolute Maximum Rating System (IEC 60134). Stress above one or more of the limiting values may cause permanent damage to the device. These are stress ratings only and operation of the device at these or at any other conditions above those given in the Characteristics sections of the specification is not implied. Exposure to limiting values for extended periods may affect device reliability.

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