Raspberry Pi I2C 16 Channel PWM / Servo & I2C 23017 16 GPIO Board





The PCA9685 is an I2C-bus controlled 16-channel LED controller optimized for LCD Red/Green/Blue/Amber (RGBA) color backlighting applications. Each LED output has its own 12-bit resolution (4096 steps) fixed frequency individual PWM controller that operates at a programmable frequency from a typical of 40 Hz to 1000 Hz with a duty cycle that is adjustable from 0 % to 100 % to allow the LED to be set to a specific brightness value.

All outputs are set to the same PWM frequency.

PCA9685 also has a built-in oscillator for the PWM control. However, the frequency used for PWM control in the PCA9685 is adjustable from about 40 Hz to 1000 Hz as compared to the typical 97.6 kHz frequency of the PCA9635. This allows the use of PCA9685 with external power supply controllers. All bits are set at the same frequency.

1. J3 Mini USB 5V input for PWM V+ & GPIO output pin10 V+

J2 2P Terminal Block 5V input for PWM V+ & GPIO output pin 10 V+

2. J1 Rs-Pi V2 GPIO output

3 JP13 DA0 ~ DA7 U14 Port A . JP14 BA0 ~ BA7 U14 Port B

4. R64,R65,R66 (for U14 Address select A0,A1,A2)

5. U14 I2C 23017 -1 Port A,B

6. U15 uln2803

7. U3 PCA9685 (PWM Port 0 ~ 15)

8. R10,R11,R12,R13,R14,R15(for U3 Address select A0,A1,A2,A3,A4,A5)

9.Red power-good V+ LED10. 1.6A PolySwitch Fuse for V+ input protect.

** for 23017 port A output you need plug in 5V to Mini USB or 2P Terminal block

1.Make sure you I2C driver are enable

To enable it all you need to do is comment out a line by putting # in front

sudo nano /etc/modprobe.d/raspi-blacklist.conf



2. Add i2c-dev in /etc/modules by use sudo nano /etc/modules

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/etc/modules: kernel modules to load at boot time.
This file contains the names of kernel modules that should be load \mathbf{z}^d
at boot time, one per line. Lines beginning with "#" are ignored. # Parameters can be specified after the module name.
snd-bcm2835
12c-bcm2708
i2c-dev
rtc-1307
tmp102
[Read 12 lines]
[^] G Get Help [^] O WriteOut [^] R Read File [^] V Prev Page [^] K Cut Text [^] C [□]
<mark>☆X</mark> Exit <mark>^J</mark> Justify <mark>^U</mark> Where Is <mark>^V</mark> Next Page <mark>^U</mark> UnCut Text <mark>^T</mark> To Spell ❤

If you already install I2c driver , then i2cdetect -y 0 i2cdetect -y 1 if Rs-Pi-v2 you need change 0 to 1

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root@raspberrypi:/home/pi# cd pwm root@raspberrypi:/home/pi/nwm# i2cdetect -v 0	^
0 1 2 3 4 5 6 7 8 9 a b c d e f 00:	
40: 41	
Adafruit_I2C.py Adafruit_PWM_Servo_Driver.py servo-41.py serv o.py Adafruit_I2C.pyc Adafruit_PWM_Servo_Driver.pyc Servo_Example.py root@raspberrypi:/home/pi/pwm# ./servo-41.py Reseting PCA9685 Setting PWM frequency to 60 Hz Estimated pre-scale: 100	
rinai pre-scale: 101	~

in i2cdetect you can found 2 device in system (21,41) 21 - 23017 41 - 9685

Next install the python-smbus python module:

```
sudo apt-get install python-smbus
sudo apt-get install i2c-tools
```

Now you are ready to use the i2c with python.

9685 test code information

http://learn.adafruit.com/adafruit-16-channel-servo-driver-withraspberry-pi/using-the-adafruit-library

23017 program information

http://nathan.chantrell.net/20120524/python-tools-for-the-mcp23017io-expander/

http://nathan.chantrell.net/20120602/raspberry-pi-io-expander-board

http://learn.adafruit.com/mcp230xx-gpio-expander-on-the-raspberrypi/hooking-it-all-up