#### **Autonics**

# ROTARY ENCODER (INCREMENTAL TYPE) **ENA/E50S8/ENC SERIES**

C€ ENA E50S8 ENC

Thank you very much for selecting Autonics products. For your safety, please read the following before using.

#### Caution for your safety

\*Please keep these instructions and review them before using this unit.

\*Please observe the cautions that follow; **Warning** Serious injury may result if instructions are not followed.

Caution Product may be damaged, or injury may result if instructions are not followed

\*The following is an explanation of the symbols used in the operation manual. ∆ caution: Injury or danger may occur under special conditions.

#### **⚠** Warning

1. When use this unit for controlling highly affective equipment to human or properties. (Medical instrument, Vehicles, Train, Airplane, combustion apparatus, entertainment etc.), it requires installing a fail safety device. It may cause serious human injury or a fire, property.

#### **⚠** Caution

- 1. Do not drop water or oil on this unit.
- 2. Please observe voltage rating.
- 3. Please check the polarity of power and wrong wiring.

n Output phase

2:A. B

2:A B

3:A, B, Z

3:A. B. 7

3

It may result in damage to this unit

Ordering information

ENA - 5000 - 2

- 4. Do not short circuit the load.
- It may result in damage to this unit

#### Outline

Series

Shaft type to

at the side

ø 50mm

shaft typ

E50S 8 - 8000

ø8mm

\*Standard:E50S8-PULSE-3-N-24

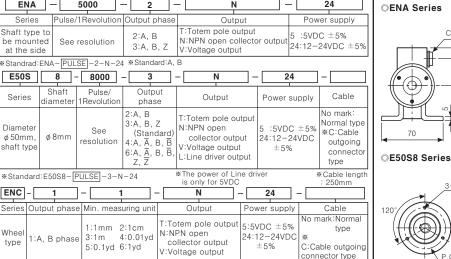
This unit is very useful to control length, angle and position by converting revolution value of shaft into number of pulse as an optical incremental Encoder.

# Dimensions

DENC Series

Cable for normal type

ø5, 5P, Length:2000, Shield cable



\*Cable length:250

#### Control output diagram

3:1m 4:0.01vd

5:0.1yd 6:1yd

Totem pole output	NPN open collector output		Voltage output		Line driver output	
Rotary encoder Load circuit connection	Rotary encoder circuit	Load connection	Rotary encoder circuit	Load connection	Rotary encoder circuit	Load connection
Source #2  Source   Load    Source   Load    Source   Load    Source   Load    Source   Load    Source   Load	Main cir	Output + Sink current: Max. 30mA		Source current: Max. 10mA Output Load 0V	Main circuit	A phase output + Ā phase output 00

F The output circuit of A, B, Z phase are the same. (Line Driver output is A, A, B, B, Z, Z)
F Totem pole output can be used for NPN open collector type(≭1) or voltage output type(

\*The above specification are changeable without notice anytime.

#### Specifications

Item			Shaft type the encoder to be mounted at the side(Incremental)	ø 50mm Shaft type Incremental Rotary encoder	Wheel type the Incremental type Rotary encoder			
Totem pole output		tem pole output	ENA-□-3-T-□	E50S83-T	ENC-1-D-T-D			
Model	NP	'N open collector output	ENA-□-3-N-□	E50S83-N	ENC-1-□-N-□			
Voltage output Line driver output		Itage output	ENA-□-3-V-□	E50S83-V	ENC-1-U-V-U			
		e driver output		E50S8				
Resolution (P/R)		R)	*1, *2, *5, 10, *12, 15, 20, 23, 25 (Note1) 125, 150, 192, 200, 240, 250, 256 1024, 1200, 1500, 1800, 2000, 200	1mm/Pulse, 1cm/Pulse, 1m/Pulse, 0.01yd/Pulse, 0.1yd/Pulse, 1yd/Pulse				
Output phase  Phase difference of output		bhase	A phase, B phase(Option : A, B, Z phase)	A phase, B phase				
		ifference of output	Output between A and B phase : $\frac{T}{4} \pm \frac{T}{8}$ (T=1cycle of A phase)					
Control	Т	Fotem pole output	<ul> <li>Low P Load current: Max. 30mA, Residual voltage: Max. 0.4VDC</li> <li>High Load current: Max. 10mA, Output voltage(Power voltage 5VDC): Min. (Power voltage-2.0)VDC,         Output voltage(Power voltage 12-24VDC): Min. (Power voltage-3.0)VDC</li> </ul>					
	- tra   1	NPN open collector output	Load	VDC				
		/oltage output	Loa	VDC				
out specification specification (F)		Line driver output		Low  Load current : Max. 20mA,     Residual voltage : Max. 0.5VDC     High  Load current : Max20mA,     Output voltage : Min. 2.5VDC				
g		Totem pole output						
Res	sponse time	NPN open collector output	Max. 1 µs (Cable length: 2m, I sink=Max. 20mA)					
(F		Voltage output						
j F	Fall)	Line driver output	<del></del>					
Ma	ax. Re	sponse frequency	300	180kHz				
Power supply			• 5VDC ±5%(Ripple P-P:Max. 5%) • 12-24VDC ±5%(Ripple P-P:Max. 5%)					
Current consumption Insulation resistance		consumption	Max. 60mA(disconnection of the load), Line driver output: Max. 50mA(disconnection of the load)					
		on resistance	Min. 100MΩ(at 500VDC between all terminals and case)					
Die	electri	c strength	750VAC 50/60Hz for 1 minute(Between all terminals and case)					
Connection			Connector connection Cable outgoing type, 250mm Cable outgoing connector type					
5 Sta	arting	torque	Max. 70gf • c	Dependent on the coefficient of friction				
M Gat	oment	of inertia	Max. 80g • cm <sup>2</sup>	(8×10 <sup>-6</sup> kg • m <sup>2</sup> )				
∺ Sh	naft loa	ading	Radial: 10kgf,	, Thrust: 2.5kgf				
g Ma	ax. allo	torque of inertia ading owable revolution	(Note2)	5000rpm				
Vibration			1.5mm amplitude at frequency of 10 ~ 55Hz in each of X, Y, Z directions for 2 hours					
Shock			Max. 75G					
Ambient temperature			-10 ~ 70℃(at non-freezing status), Storage: -25 ~ 85℃					
Ambient humidity			35 ~ 85%RH, Storage: 35~90%RH					
Protection			IP50(IEC standard)					
Cable			ø5mm, 5P, Length:2m, Shield cable	ø 5mm, 5P, Length:2m, Shield cable (Line driver output: ø 5mm, 8P)	ø5mm, 5P, Length:2m, Shield cable			
ccesso	ory		ø10mm coupling	ø8mm coupling, Bracket				
eight /			Approx. 345g	Approx. 275g	Approx. 494g			
Approval			(€ (Except Line driver output)					

\*\*(Note2)Max. allowable revolution  $\geq$  Max. response revolution [Max. response revolution(rpm) =  $\frac{\text{Max. response frequency}}{2} \times 60 \text{ sec}$ ]

4 holes Connector(SCN16-4P)

Cable for normal type

2- ø 5.5

(Unit:mm)

(SCN16-5P)

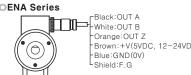
Wheel circumference Min. measuring unit

228.6mm(0.25yd) 0.01yd, 0.1yd, 1yd

1mm, 1cm, 1m

Please select the resolution to make lower max, revolution than max, allowable revolution

## Connections



\*Non-using wires must be insulated.

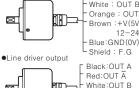
\*The shield cable and metal case of encoder must be grounded(F.G).

- Black : OUT A

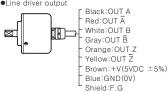
#### E50S8 Series

Voltage output

Totem pole output/ NPN open collector output,

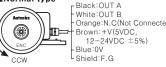


- White: OUT B Orange: OUT Z Brown:+V(5VDC 12-24VDC ±5%) Blue:GND(0V)

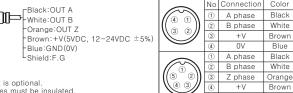


Non-using wires must be insulated ★The shield cable and metal case of encoder must be grounded (F.G.)

#### ENC Series ■Normal type



\*Non-using wires must be insulated \*The shield cable and metal case of encoder must be grounded(F.G).



■Cable outgoing connector type

 Totem pole output Voltage ou





0V

NPN	open colle age output	ector output	Line driver output			
Pin No	Cable color	Function	Pin No	Cable color	Function	
1	Black	OUT A	1	Black	OUT A	
(2)	White	OUT B	2	Red	OUT Ā	
(3)	Orange	OUT Z	3	Brown	+V	
4	Brown	+V	4)	Blue	GND	
(5)	Blue	GND	(5)	White	OUT B	
(6)	Shield	F.G	6	Gray	OUT B	
			7	Orange	OUT Z	
			(8)	Yellow	OUT Z	
			9	Shield	F.G	

#### ■Cable outgoing connector type



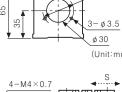
	Pin No	Cable color	Function	
	1	Black	OUT A	
	2	White	OUT B	
ŀ	3	Orange	N.C	
F	4	Brown	+V	
	(5)	Blue	GND	
	6	Shield	F.G	

## Accessary

# •Bracket(E50S8 Series)

Coupling(ENA/E50S8 Series)





(Unit:mm

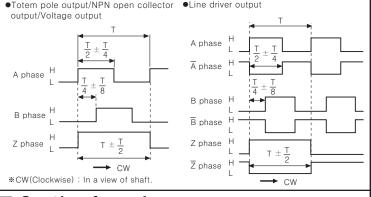
АВ ENA ø10mm coupling | ø10 +0.1 | ø22 | 18.2 | 2 50S8 ø8mm coupling ø8 +0.1 ø19 18.2 2

•When combine the coupling to encoder shaft, if there is big eccentricity or bend between rotating encoder shaft and mate shaft, it will make the life cycle of encoder and coupling

•It must not use larger shaft loading than specification

#### Output waveform

●Totem pole output/NPN open collector ●Line driver output



## Caution for using

1. Installation

1) This unit is consisted of precision components. Therefore please treat this product carefully.

②When you install this unit, if eccentricity and deflection angle are larger, it may

shorten the life cycle of this unit. (ENA, E50S8) ③Please mount this unit on panel with lowest the coefficient of friction between rotating detection part and target. It may shorten the life cycle of this unit. (ENC)

(Do not put strong impact when insert coupling into shaft. (ENA, E50S8)

①Please use attached SIL Twist pair wire and use proper receiver for RS-422A

communication. ②Do not connect and cut circuit off during power on.

It may result in damage to this unit.

③When the power source is a Switching power, please install the surge absorber in power line and wire should be shorter in order not to be influenced by noise.

Environment Please do not use this unit with below environment, it results in malfunction.

①Place where this unit or component may be damaged by strong vibration or impact.

@Place where there are lots of flammable or corrosive gases. 3 Place where strong magnet field or electric noise are occurred

(4) Place where is beyond of rating temperature or humidity.

⑤Place where strong acids or alkali near by. 4. Vibration and Impact

①When the strong impact loads on this unit, the error pulse may occur as if the slit is revolving

@Encoder with high resolution can be easily affected by vibration, therefore fix the sub mounting metallic ball when install this unit.

Wire connection

1) Do not draw the wire with over 30N strength after wiring

②When a high voltage or power line pass near by the encoder cable, be sure to wire the encoder cable in separated conduit to prevent malfunction.

\*It may cause malfunction if above instructions are not followed.

# Major products

■ PROXIMITY SENSOR ■ PHOTOELECTRIC SENSOR ■ AREA SENSOR

■ FIBER OPTIC SENSOR ■ DOOR/DOOR SIDE SENSOR ■ PRESSURE SENSOR

■ ROTARY ENCODER ■ COUNTER

■ TIMER ■ TEMPERATURE CONTROLLER ■ TEMPERATURE/HUMIDITY TRANSDUCER

POWER CONTROLLER 
PANEL METER

■ TACHO/LINE SPEED/PULSE METER ■ DISPLAY UNIT ■ SENSOR CONTROLLER

■ SWITCHING POWER SUPPLY

■ GRAPHIC PANEL

■ 5-PHASE STEPPING MOTOR & DRIVER & CONTROLLER

■ LASER MARKING SYSTEM(CO<sub>2</sub>, Nd:YAG)

Autonics Corporation

VERSEAS SALES OVERSEAS SALES : Bldg. 402 3rd Fl., Bucheon Techno Park, 193, Yak Wonmi-gu, Bucheon-si, Gyeonggi-do, 420-73 TEL:82-32-610-2730 / FAX:82-32-329-0728

EP-KE-09-0010G