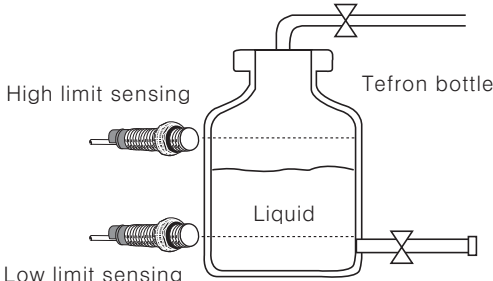
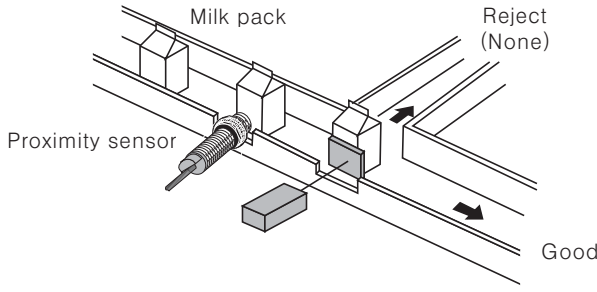
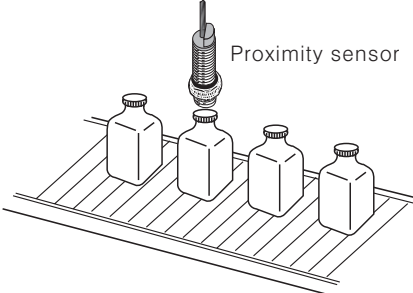
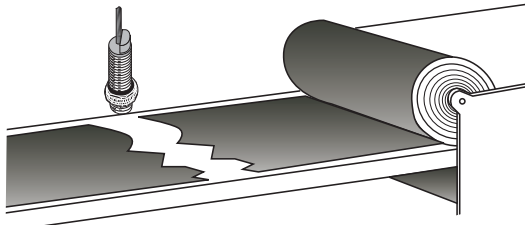
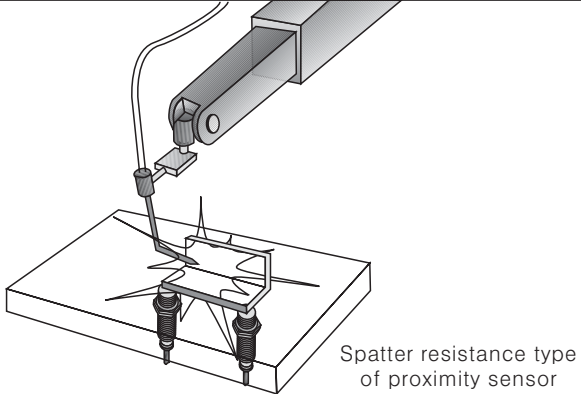
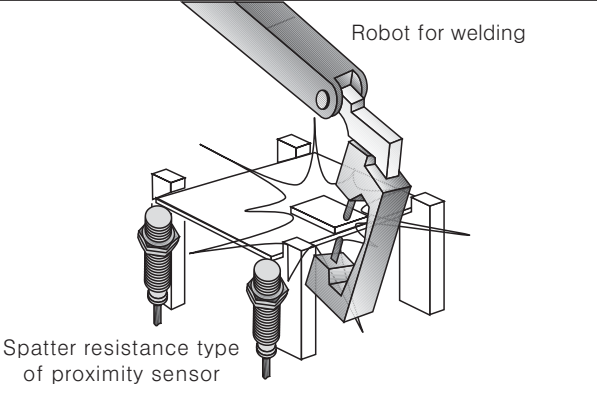
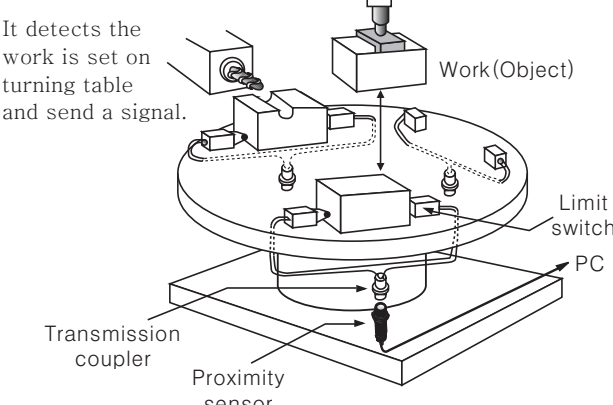
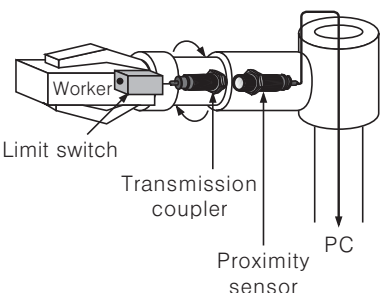
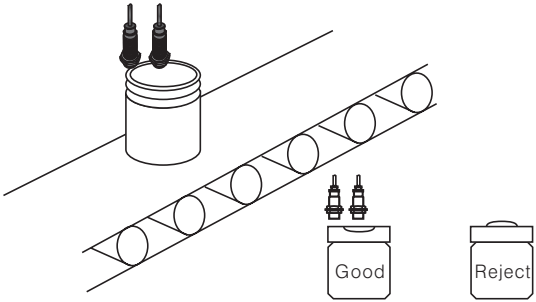
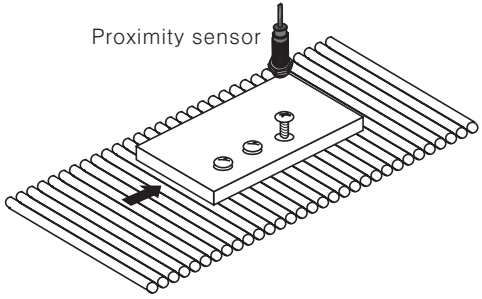
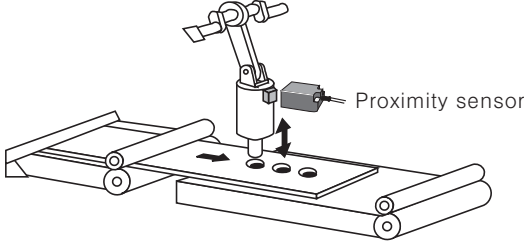
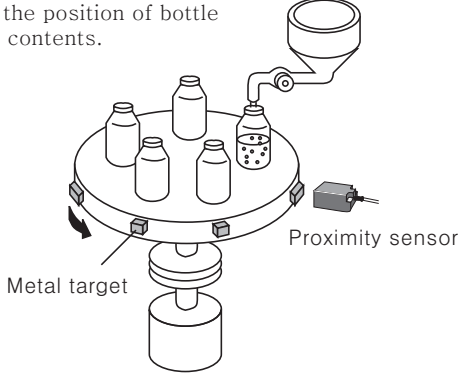
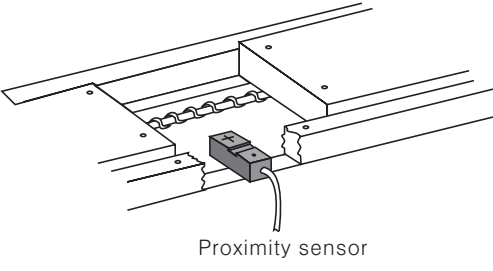
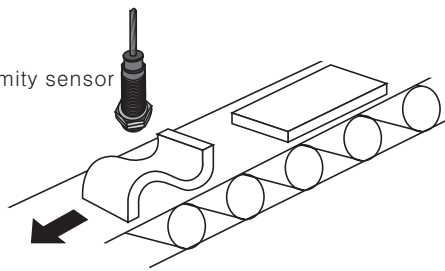
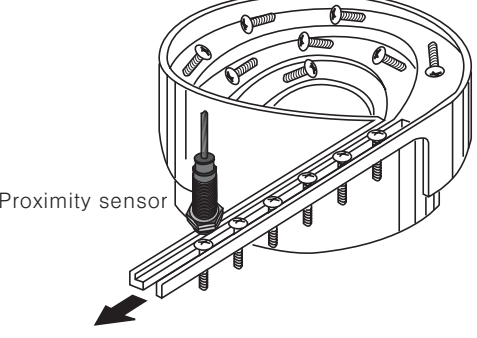


■ Applications

<p>Detection of liquid level(Capacitive type)</p> <p>It is able to detect the level of liquid inside of bottle from outside.</p>  <p>High limit sensing</p> <p>Tefron bottle</p> <p>Liquid</p> <p>Low limit sensing</p>	<p>Detecting Milk in paper pack(Capacitive type)</p> <p>It is able to detect milk in side of pack by capacitive proximity sensor.</p>  <p>Milk pack</p> <p>Proximity sensor</p> <p>Reject (None)</p> <p>Good</p>	(A) Counter
<p>Detection of cap of bottles(Capacitive)</p>  <p>Proximity sensor</p>	<p>Detection of band detectives(Capacitive)</p>  <p>Proximity sensor</p>	(B) Timer
<p>Fixing the point to be welded(Arc)</p>  <p>Spatter resistance type of proximity sensor</p>	<p>Checking the position for Spot welding</p>  <p>Robot for welding</p> <p>Spatter resistance type of proximity sensor</p>	(C) Temp. controller
<p>Turning table(Transmission coupler)</p> <p>It detects the work is set on turning table and send a signal.</p>  <p>Work(Object)</p> <p>Limit switch</p> <p>PC</p> <p>Transmission coupler</p> <p>Proximity sensor</p>	<p>Transmitting the signal of checking(Transmission coupler)</p> <p>It detects if the robot arm is holding the work and send a signal.</p>  <p>Worker</p> <p>Limit switch</p> <p>Transmission coupler</p> <p>Proximity sensor</p> <p>PC</p>	(D) Power controller
		(E) Panel meter
		(F) Tacho/ Speed/ Pulse meter
		(G) Display unit
		(H) Sensor controller
		(I) Switching power supply
		(J) Proximity sensor
		(K) Photo electric sensor
		(L) Pressure sensor
		(M) Rotary encoder
		(N) Stepping motor & Driver & Controller
		(O) Graphic panel
		(P) Field network device
		(Q) Production stoppage models & replacement

Applications

■ Applications

<p>Detecting condition of cans</p> <p>Proximity sensor</p> 	<p>Measuring the height of screw</p> <p>Detecting the status of screw</p> <p>Proximity sensor</p> 
<p>Controlling a press</p> <p>Making a hole on panel by constant distance</p> <p>Proximity sensor</p> 	<p>Positioning control</p> <p>Detecting the position of bottle for fill the contents.</p> <p>Proximity sensor</p> <p>Metal target</p> 
<p>Detecting position of target</p> <p>Automatic assembly conveyor line</p> <p>Proximity sensor</p> 	<p>Sensing incorrect shape of target</p> <p>Proximity sensor</p> 
<p>Counting screws</p> <p>Proximity sensor</p> 	<p>Detecting position of target(PFI 25)</p> <p>Automatic assembly conveyor line</p> <p>Proximity sensor</p> 